

JCRAI 2026

中国·北京
11月6-8日

2026年第六届机器人与人工智能国际会议

2026 6th International Joint Conference on Robotics and Artificial Intelligence

 www.jcrai.org

 email@jcrai.org

Welcome to JCRAI 2026

We invite you to join the 2026 6th International Joint Conference on Robotics and Artificial Intelligence (JCRAI 2026), which will take place in Beijing, China during November 6-8, 2026. This conference is a forum for researchers, scientists, engineers and industry professionals to share the latest advances in the field of Robotics and Artificial Intelligence.

Conference Committee

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Weiye Wang, Beijing Information Science and Technology University, China

Important Dates

Final Round

- Abstract Submission Due: September 20, 2026
- Full Paper Submission Due: October 5, 2026
- Main Conference: November 6-8, 2026

Call For Papers

The topics of interest include, but are not limited to:

ARTIFICIAL INTELLIGENCE

- Agents and Multi-Agent Systems
- Expert Systems
- Fuzzy Logic

AMBIENT INTELLIGENCE

- Ambient Assisted Living
- Data Science
- Intelligent Driving

ROBOTICS

- Assistive Robots
- Autonomous Robots
- Creative and Entertaining Robots

MACHINE VISION

- Augmented Reality
- Bioinformatics
- Human Computer Interaction

Keynote Speaker



Prof. Tao Zhou

North Minzu University, China

Submission Guidelines

We are pleased to accept original and unpublished paper submissions from professors, doctors, PhD. students, teachers, engineers, industry researchers, and other academic experts for JCRAI 2026.

Online Submission System:

<https://cmt3.research.microsoft.com/JCRAI2026>

Publication Information

Registered and presented full papers will be included in the JCRAI 2026 digital conference proceedings, which will be published by Springer Book Series Lecture Notes in Networks and Systems (ISSN: 2367-3389), and also submitted to major citation databases (including, but not limited to Ei Compendex and Scopus) for review and indexing.



Springer



Compendex on
Engineering Village

Scopus

Call for Special Session Submissions

Special Session I : Deep Learning-Driven Machine Vision Technology and Applications

Special Session II : AI-Empowered Change Control for Product Supply Chain Systems Subject to Security Threats

Special Session III: Vision-Driven Embodied Intelligence for Robot Navigation and Manipulation

Special Session IV: Research on Key Technologies of Humanoid Robotics

Special Session V : AI Methodologies and Applications in Pattern Recognition and Machine Learning

Special Session VI: Frontiers in AI for Remote Sensing: Image Processing and Target Detection

Special Session VII: Multimodal Information Perception and Human- Machine Interaction

Special Session VIII: Advances in Image Computing

Special Session IX: Motion Decision-making of Unmanned Equipment Driven by Deep Intelligence

Special Session X : Macro-Micro-Nano Robotic Actuation and Intelligent Sensing

Special Session XI: Multimodal Perception and Manipulation Skill Learning for Embodied Intelligent Robots in Task-Oriented Scenarios

Special Session XII: Agent Interconnection and Collaboration Intelligence



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